

Feature learning for interpretable, Performant Decision Trees

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Property of Decision Tree

- Decision Tree :

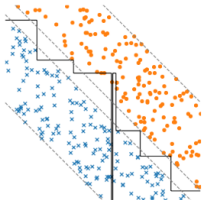
depth ↓ ► Performance ↓, Interpretable ↑

depth ↑ ► Performance ↑, Interpretable ↓

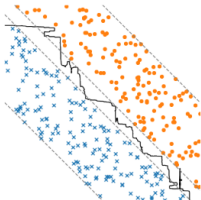
- No matter how much the depth is increased, the performance on test data does not significantly outperform other models.

- They propose an algorithm that, through **feature learning**, generates a single tree with an appropriate depth for a Decision Tree while achieving good performance.
- **Feature learning** means that in the decision tree training, instead of $X_j \leq c$, the algorithm contemplates $f(\mathbf{X}) \leq c$, and learning f during the training process where $\mathbf{X} = (X_1, \dots, X_p)'$.

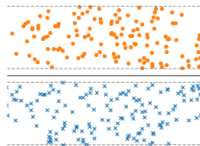
Example of feature transformation



(a) A decision tree is relatively complex and generalizes poorly.



(b) A random forest is very complex and generalizes better, but not perfectly.



(c) After rotation, a decision tree is simple and generalizes perfectly.

- Above picture demonstrates that through feature transformation, a single tree can achieve good performance.

Proposed method

- They propose alternating between learning a tree, similar to the CART, and performing feature learning based on gradients.
- For the feature learning, they consider Kernel Density Decision Tree(KDDT) which is differentiable.

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Fuzzy Decision Tree(FDT)

Problem of conventional Decision Tree(CART) :

Rule : If $X \leq 3000$, X is classified as group A else B.

Then, $X = 2999$ and $X = 3001$ are classified as different group.

- This causes prediction errors for Decision Trees near the boundaries
- If CART deterministically split data into child node, FDT reflect the possibility of data being split into each child node (e.g., using probabilities)

- Crisp Decision Tree : CART

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Kernel Density Decision Tree(KDDT)

- KDDT is a model that expresses the likelihood of splitting into child nodes using a kernel to represent probabilities.
- Note that unlike CART, KDDT is the differentiable model.

Example

Let $X \in \mathbb{R}$ be a input vector. Then, we have

$\mathbb{I}(X \in [a_j, b_j]) \rightarrow F(X - a_j) - F(X - b_j)$ where F is cdf of normal.

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- Any differentiable parameterized class of feature transforms can be used.
- example : Linear transformation $\mathbf{X} \rightarrow A\mathbf{X} + b$
- When training rule in the KDDT, feature learning is conducted based on gradient method for the impurity measure.

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- In the KDDT paper, they proposed the method for converting fuzzy decision trees to crisp decision trees, and it seems to be employed here.
- However, the details are not elaborated upon, and there is no code available.
- Note that the performance slightly degrades during the converting.

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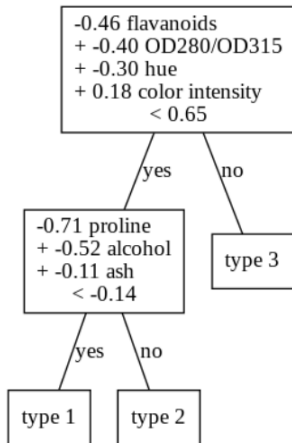
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Experiments

data <i>n, p, q</i>	LR	MLP	DT	RF	ET	XGB	ours:	
							fuzzy	linear crisp
iris [18] 150, 4 (4), 3	0.960	0.953	0.947	0.947	0.953	0.947	0.960	0.960
heart-disease [30] 303, 13 (20), 2	0.822	0.792	0.707	0.802	0.795	0.792	0.812	0.812
dry-bean [31] 13611, 16 (16), 7	0.925	0.934	0.912	0.923	0.921	0.928	0.920	0.913
wine [1] 178, 13 (13), 3	0.983	0.989	0.904	0.977	0.989	0.955	0.983	0.983
car [5] 1728, 6 (21), 4	0.926	0.992	0.977	0.964	0.971	0.994	0.991	0.992
wdbc [44] 569, 30 (30), 2	0.974	0.975	0.935	0.965	0.970	0.968	0.972	0.972
sonar [38] 208, 60 (60), 2	0.755	0.879	0.735	0.826	0.880	0.855	0.818	0.799
pendigits [2] 10992, 16 (16), 10	0.952	0.994	0.964	0.993	0.994	0.991	0.981	0.976
ionosphere [39] 351, 34 (34), 2	0.875	0.917	0.892	0.934	0.943	0.943	0.932	0.920

- Even as a single tree, proposed model performs well.

Experiments



- The above results is from converted crisp proposed model.